

Supergen



Offshore
Renewable
Energy

Early Career Researcher Posters and Abstracts Booklet

2026 Annual Assembly

Surnames H-L



Engineering and
Physical Sciences
Research Council



Early Career Researcher Posters 2026

Payvand Habibi, University of Strathclyde

Advanced Stress Analysis for Optimised Marine Energy Structures (ASAMES)

Payvand Habibi, University of Strathclyde

An Integrated Experimental-Computational Framework for Erosion Analysis of Tidal Turbine Blades

Yadong Han, University of Oxford

Unsteady hydrodynamic forces on a forced oscillating rotor

Anna Holcombe, University of Exeter

Assessing the contribution of VIV to fatigue damage in dynamic power cables

Sam Hughes, University of Edinburgh

Reduced-Order Modelling (ROM) of Tidal Turbine Rotor Blade Structures

Jack Lewis, University of Strathclyde

Offshore Wind Farm Layout Optimisation using Simplified Geometric Blockage Metrics

Ye Li, University of Southampton

Concrete Composites in Marine Environment, FRP-enabled sustainable concrete for durable floating wind structures

Chenyang Liu, University of Oxford

Origami-Enhanced Dielectric Fluid Generator for Wave Energy Conversion

Background

Wind farm layout optimisation (WFLO) often relies on complex wake models or computationally intensive algorithms to improve turbine placement and maximise energy output. This study explores a lightweight alternative, using simple, physics-informed geometric blockage metrics: **Blockage Ratio (BR)** and **Blockage Distance (BD)**, as direct reward functions for machine learning-based optimisation.

By integrating these metrics with common optimisation methods, we assess whether such low-cost approximations can produce layouts comparable to those designed using traditional, more computationally demanding methods.

Wake Modelling

Current market FLOW and monopile OFW devices were simulated using a combination of a Gaussian velocity model and the Crespo-Hernandez wake model to account for wake effects and velocity deficits. The simulation was performed using the FLORIS model developed by NREL.

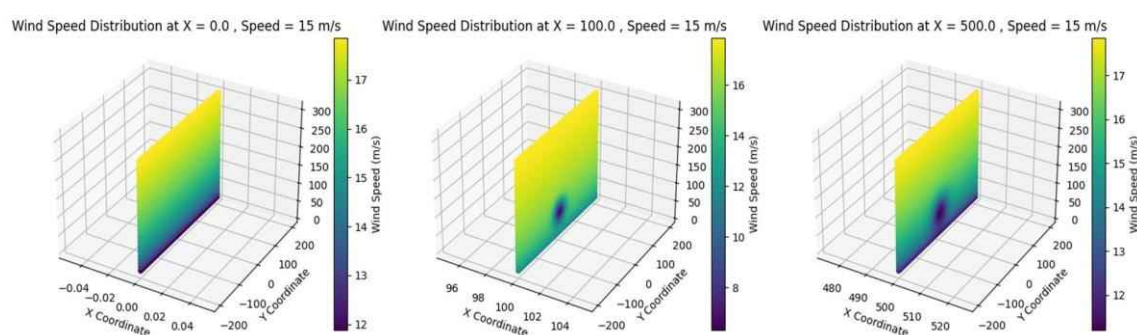


Fig 1: Slices through the FLORIS domain showing the wake expansion of an OWT

Methodology

We use a Genetic Algorithm (GA), Particle Swarm Optimisation (PSO), and a Reinforcement Learning (RL) agent using Soft Actor-Critic (SAC) as our optimisation methods, due to their prevalent use across WFLO literature.

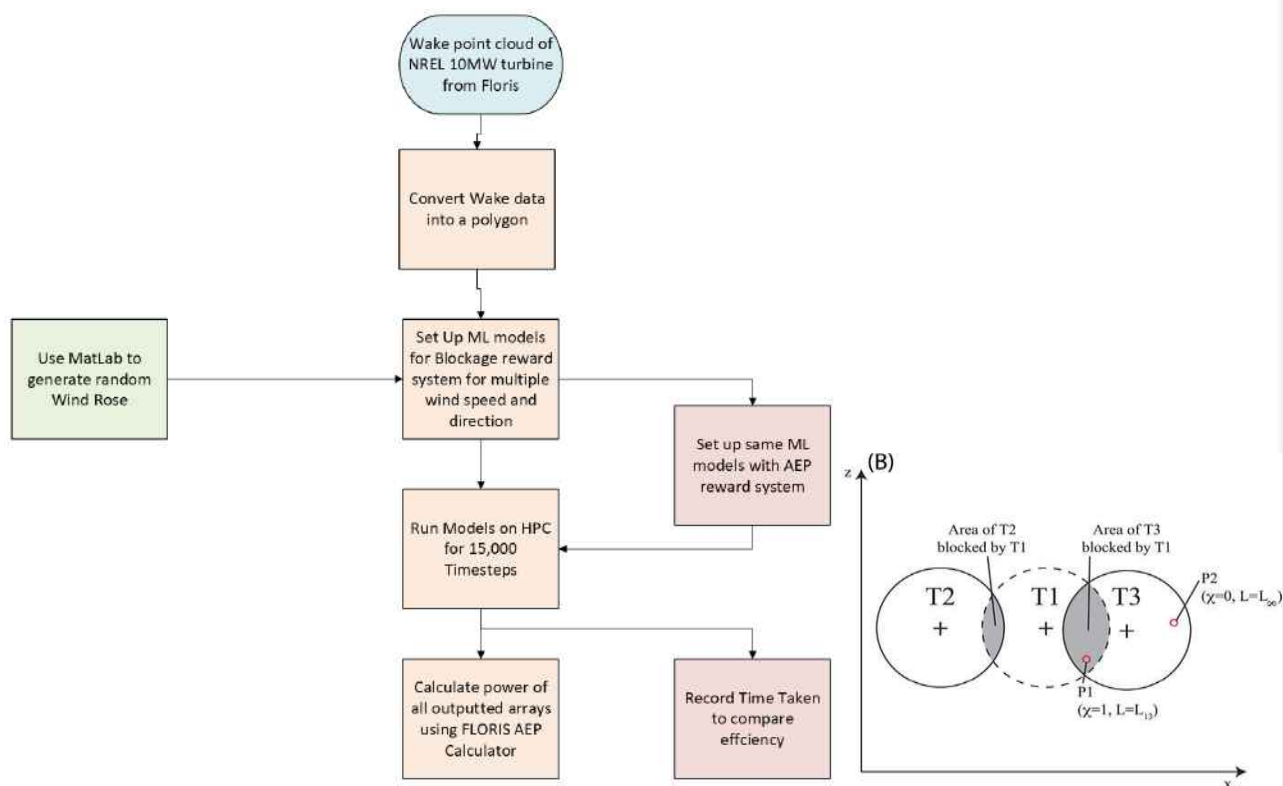


Fig 2: Flowchart showing project pipeline

Fig 3: Representation of wind turbines and the related blockage variables

The Blockage reward functions are the optimal Blockage Ratio (BR), as close to zero as possible, and Blockage Distance (BD), as close to one as possible. The relevant equations are presented here:

$$BR = \frac{1}{A} \int_{(x,y) \in A} X dx dy \quad BD = \frac{1}{A} \int_{(x,y) \in A} [L_X + (1 - X)L_X] dx dy$$

Results

With a wind Rose as the input wind data, the AEP reward systems slightly outperformed their blockage reward system counterparts. However, the Blockage-based GA and PSO produced more efficient layouts compared to the staggered baseline, as shown in Figure 4.

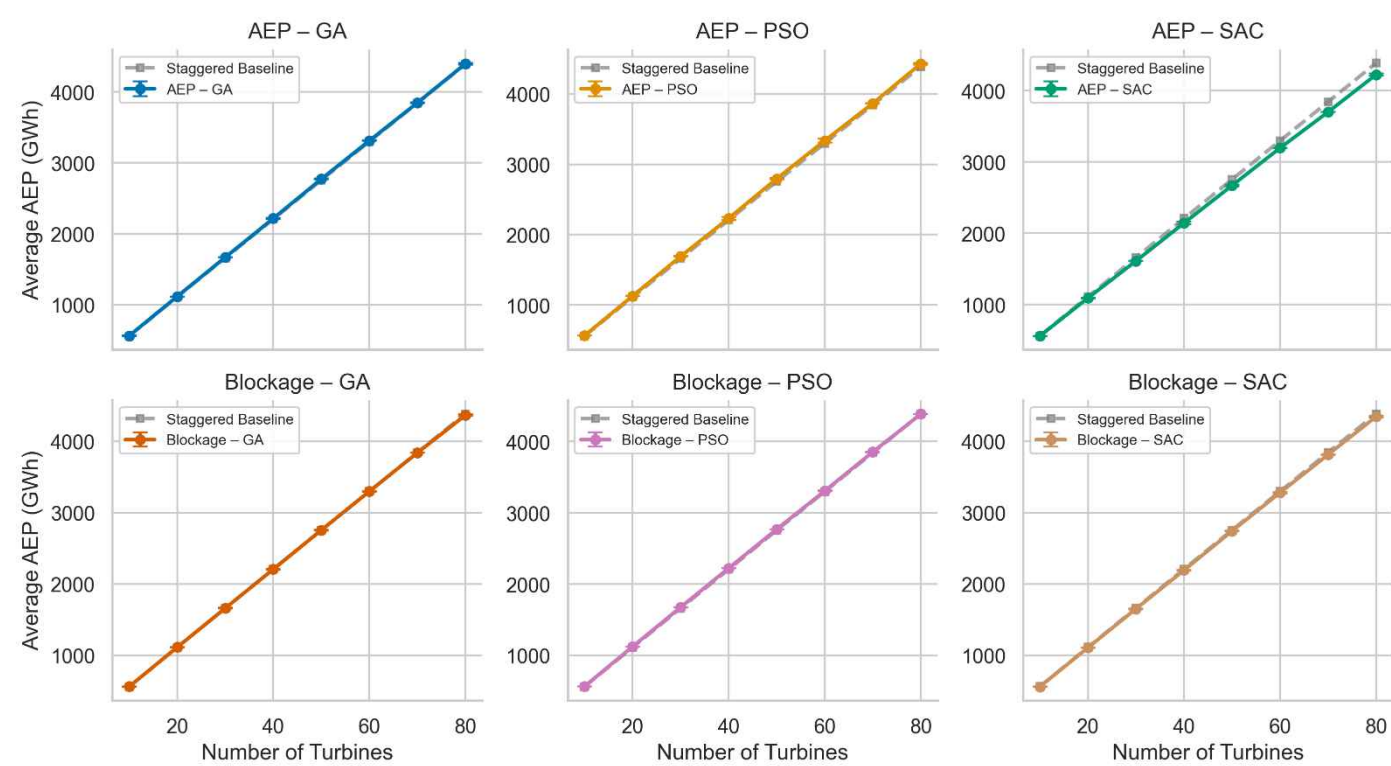


Fig 4: Power Output of all generated turbine configurations

In addition, as shown by Figure 5 below, the Blockage methods were significantly faster than their AEP counterparts, ranging by orders of magnitude of 0.9 – 1.12.

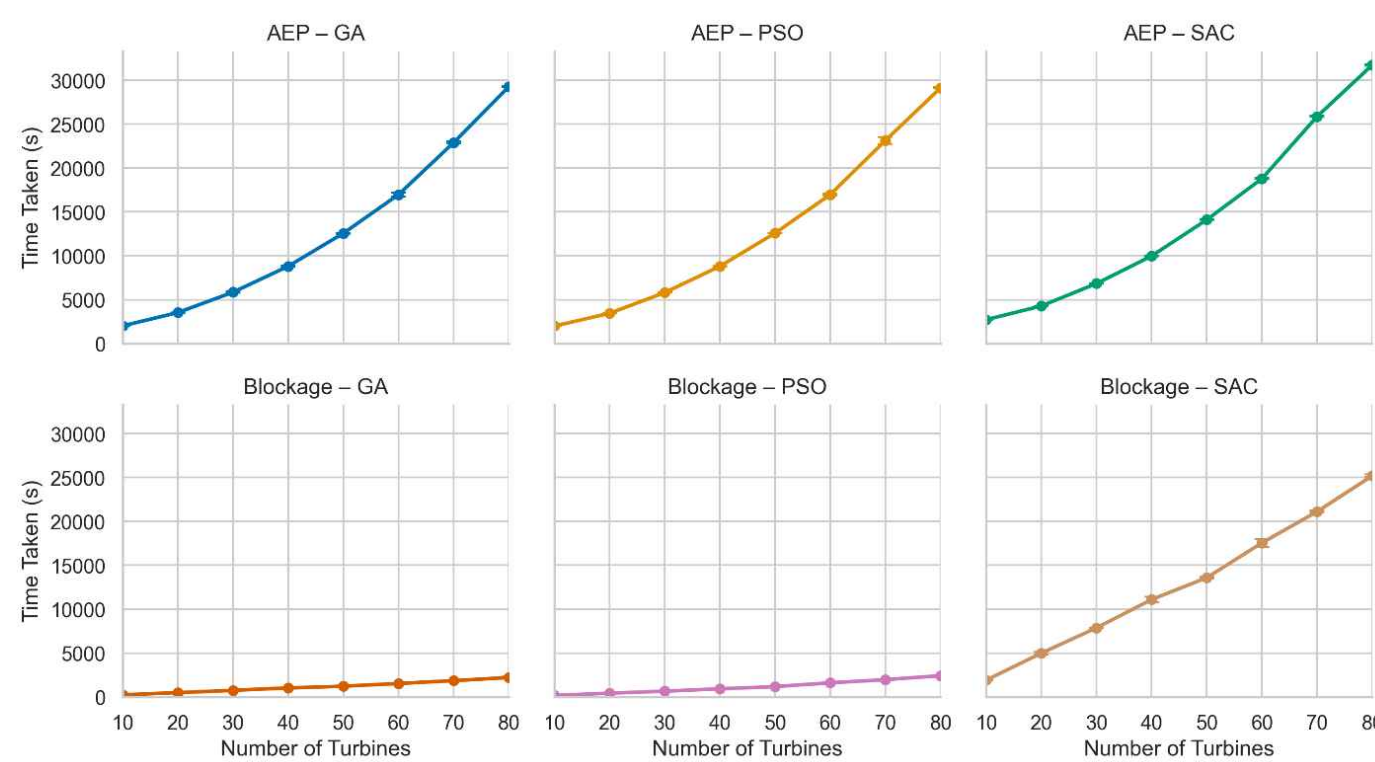


Fig 5: Average time to produce the generated OWF configurations

Discussion and Further Work

Results show that using blockage metrics as a reward function is highly effective and can yield results comparable to standard methods. All machine learning methods achieved significant reductions in optimisation time, which becomes increasingly valuable when scaling to realistic OWF. The simplicity of the blockage framework also supports easy adaptation to varying wind directions and speeds, and it can be extended to floating wind scenarios with only adjustments to wake polygon sizes.

References

- Duvvuri, G.M. et al. (2022) 'Further calibration and validation of FLORIS with wind tunnel data', Journal of Physics: Conference Series, 2265(2), p. 022019.
- Ti, Z., Deng, X.W. and Yang, H. (2020) 'Wake modeling of wind turbines using machine learning', Applied Energy, 257, p. 114025.
- Yan, C., Pan, Y. and Archer, C.L. (2019) 'A general method to estimate wind farm power using artificial neural networks', Wind Energy, 22(11), pp. 1421–1432.

Concrete Composites in Marine Environment

FRP-enabled sustainable concrete for durable floating wind structures



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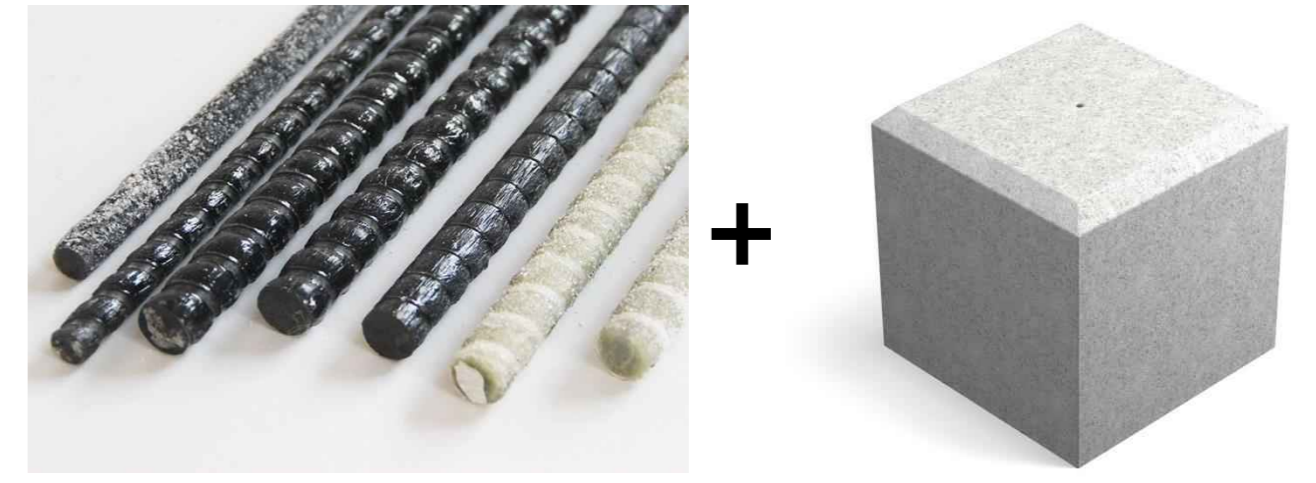
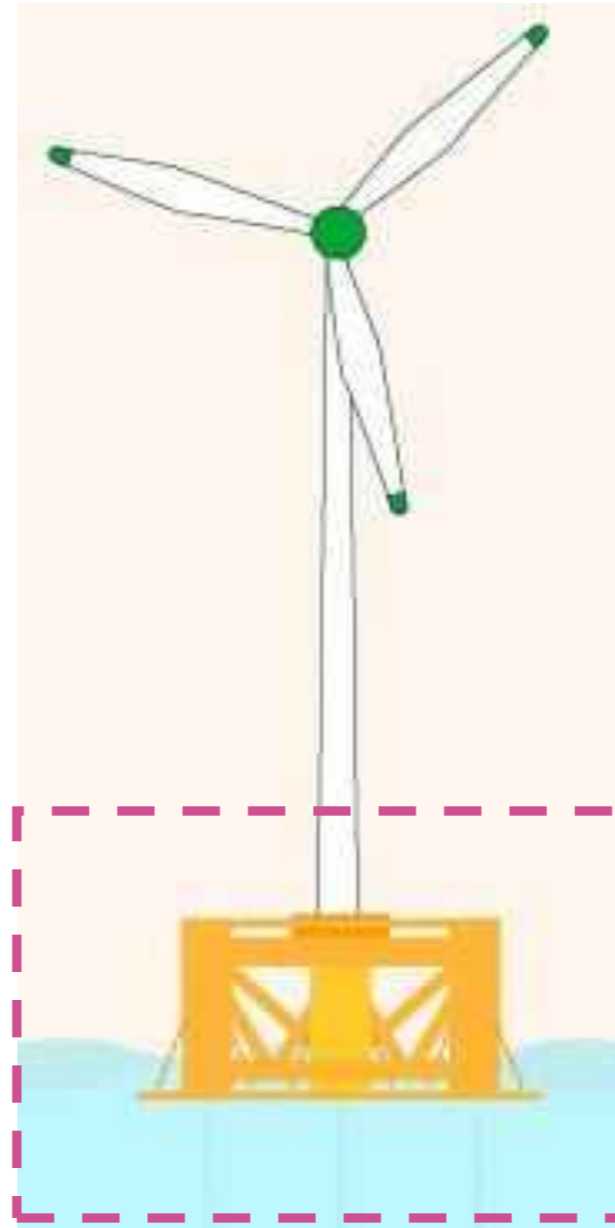
Opportunities for the application of concrete

Requirements for FOW structure

- Harsh Marine Environment (Corrosion)
- Complex Loading Conditions (cyclic fatigue)
- Long-Term Durability Uncertainty (maintenance)
- Cost & Deployment Constraints
- External Supply Chain Uncertainty



Concrete and FRP offer a cost-effective, durable, and locally available solution for next-generation floating wind structures.

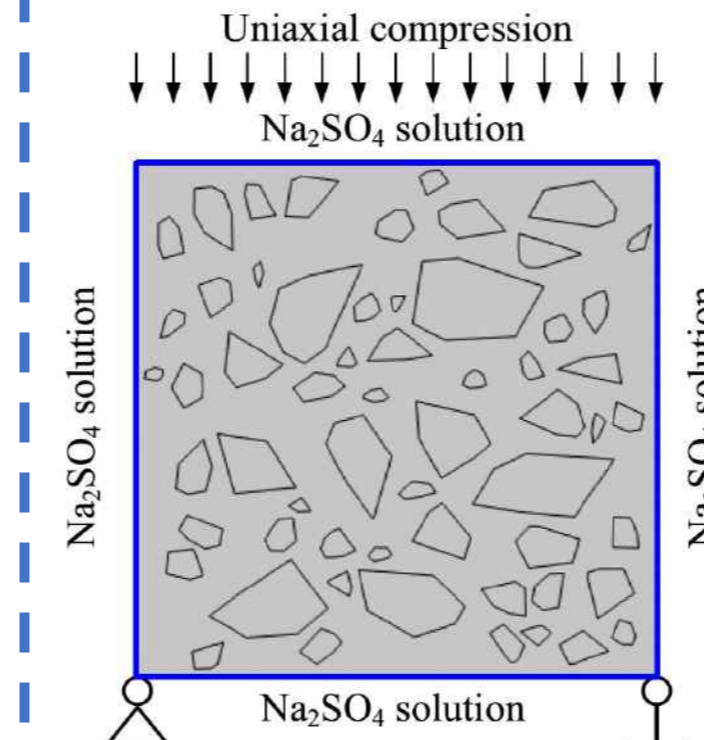
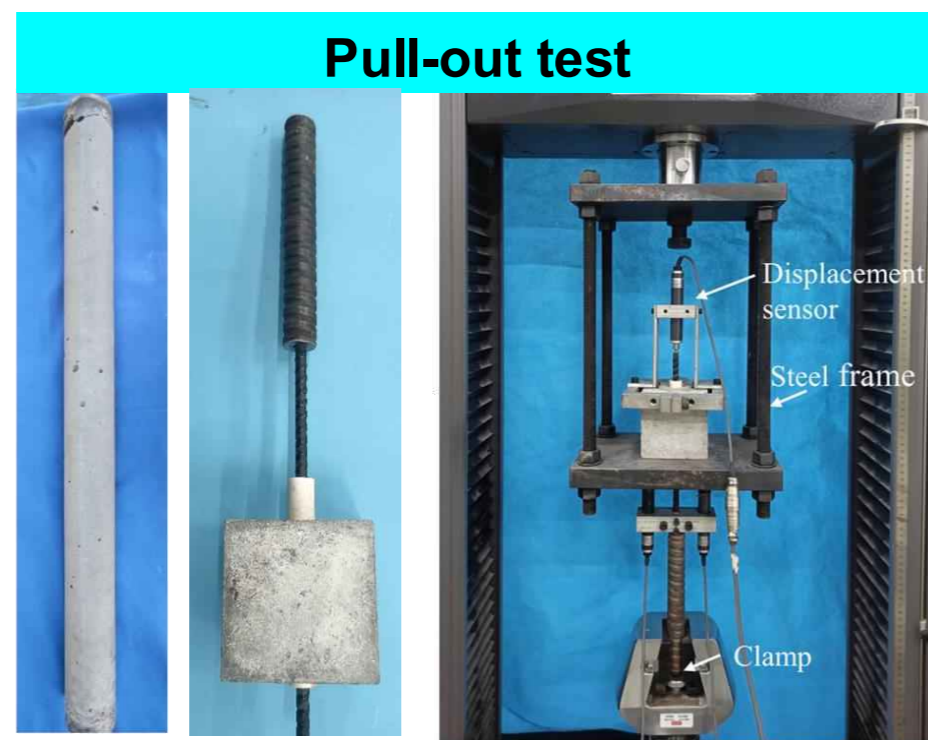
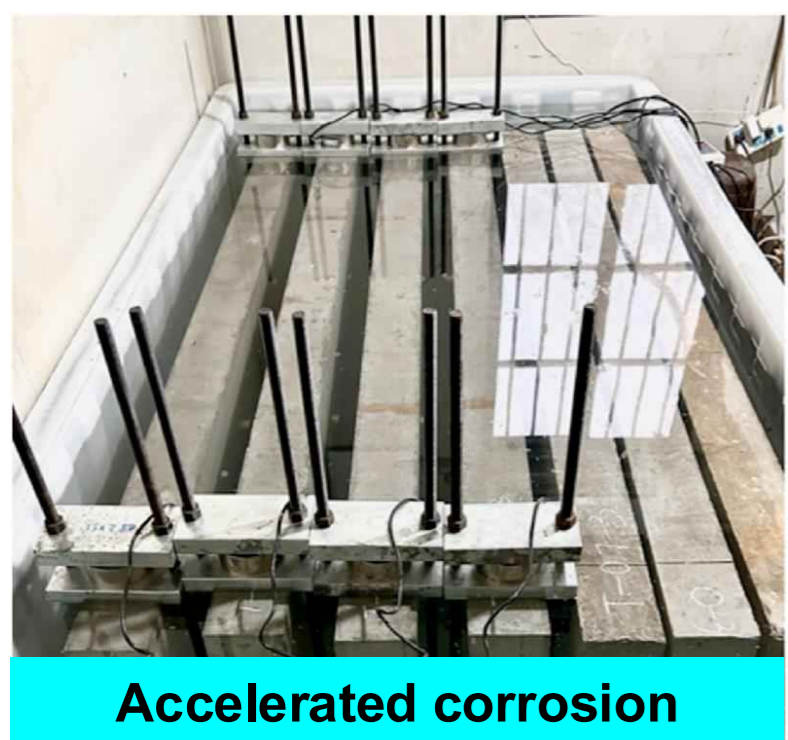


FRP reinforcement offers high strength and removes corrosion constraints, enabling a new design space for sustainable concrete systems, i.e., incorporating low-carbon cements, seawater use, and recycled materials.

Opportunities for Concrete Replacement

Lower Tower Sections
Columns
Pontoons
Ballast compartments
Working platforms

Concrete Degradation Model and FRP-concrete Structural Durability



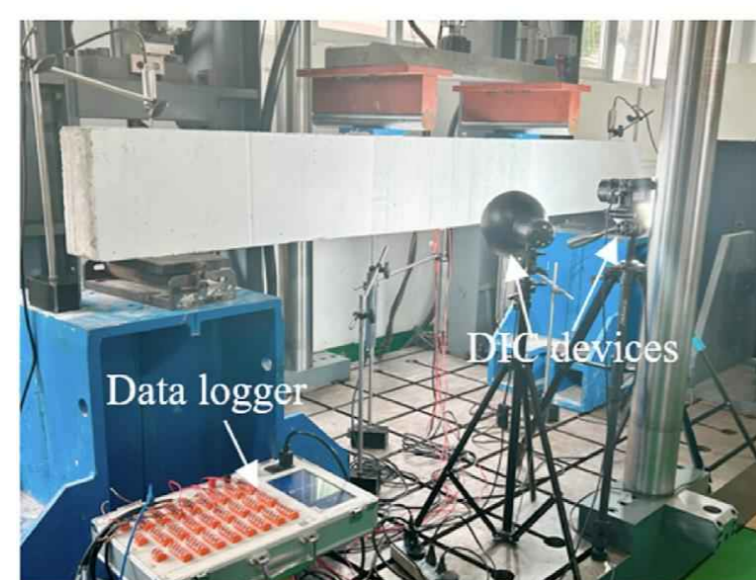
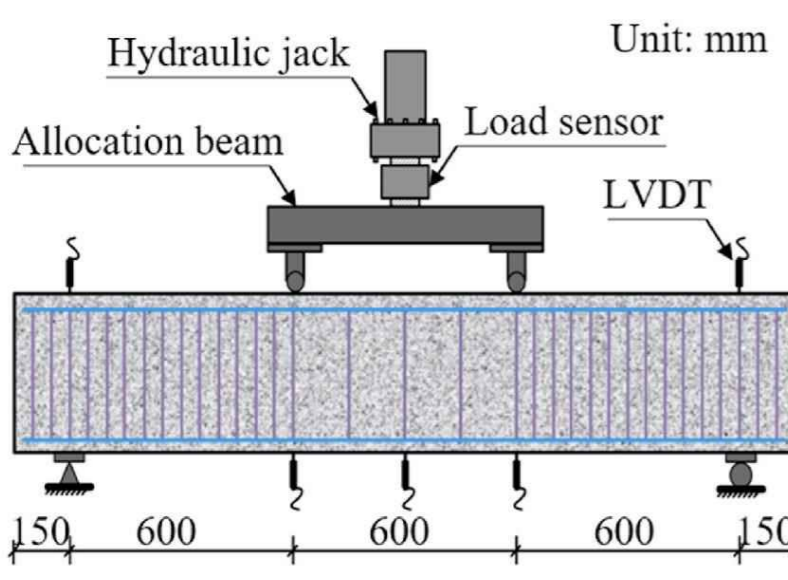
$$\frac{\Delta V}{V} = \left(\frac{\Delta V}{V}\right)_{\text{APr}} - \left(\frac{\Delta V}{V}\right)_{\text{leach}} \quad \text{Phase change} \rightarrow \text{Volume change}$$

$$\epsilon_v = \frac{\Delta V}{V} - f \cdot \phi_0 \quad \text{Volume} \rightarrow \text{Micro strain}$$

$$\epsilon^M = \frac{9\phi_m K_p}{3K_p + 4G_s} \epsilon_R \quad \text{Micro strain} \rightarrow \text{Macro equivalent strain}$$

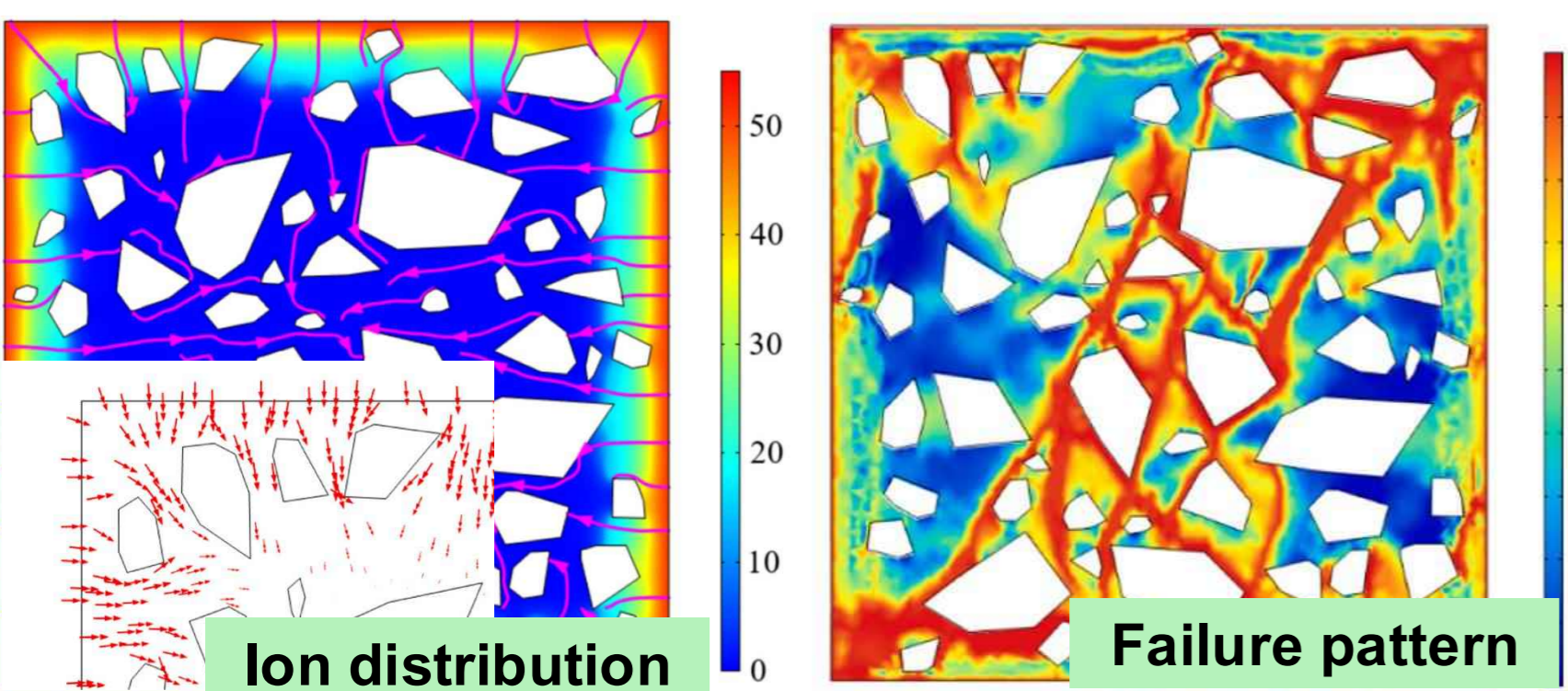
$$\sigma = (1-d)C : (\epsilon - \epsilon^M) \quad \text{Strain/stress relation} - \text{Damage}$$

A mesoscale mechanical deterioration model for the chemo-transport-mechanical degradation of concrete.

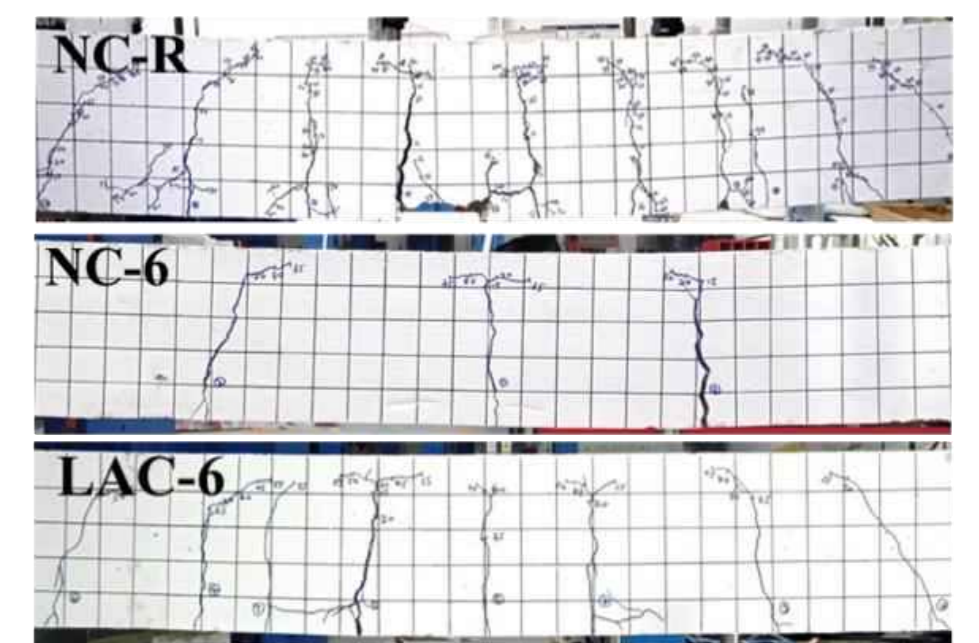
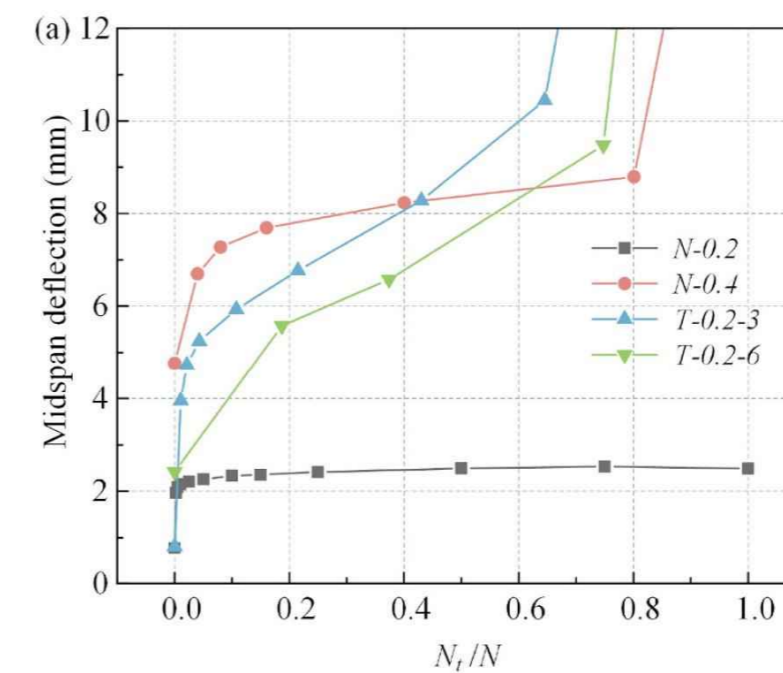
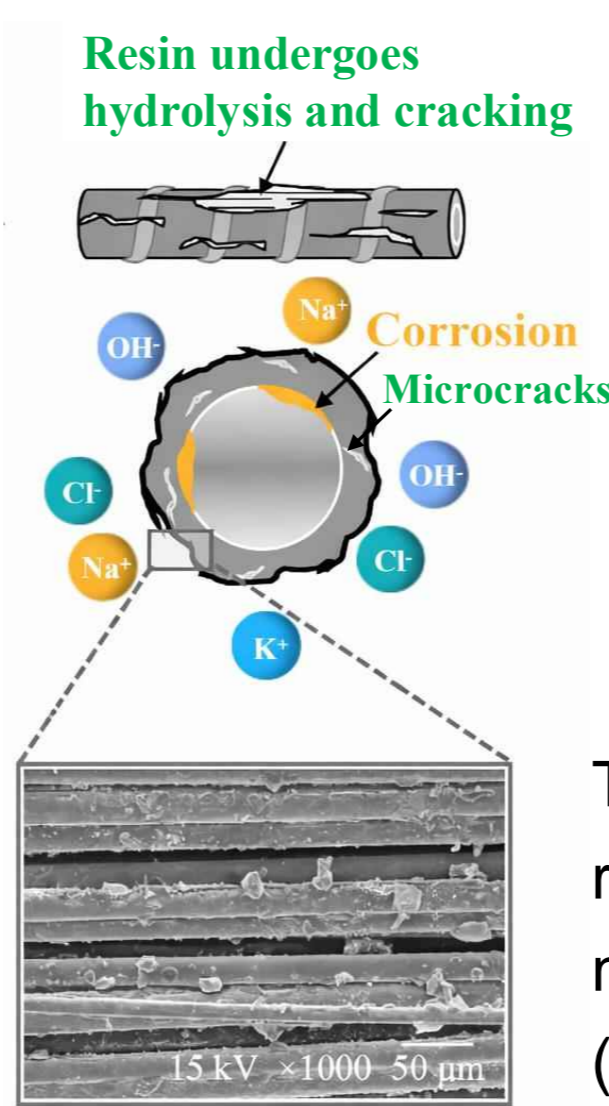


Degradation of FRP, concrete, and composite beams was investigated after exposure to seawater immersion, sustained loading, and high temperature.
Concrete: Normal/Low-carbon concrete using seawater
Rebar: steel-FRP composite bar
Accelerated corrosion: seawater, 0.5 cracking load, 50°C
Test: FRP fracture, Pull-out, Beam bending, Beam fatigue tests (0.4 capacity)

Results and implication



The model successfully predicts expansion-driven degradation and reproduces observed failure modes, demonstrating that aggregate-induced heterogeneity controls sulfate transport, stress concentration, and crack propagation paths.



The epoxy in FRP in low-carbon concrete showed significantly reduced decomposition depth to only 300 μm. The beams maintained consistent yielding loads and higher ultimate loads (64.0% and 89.8% greater than the normal concrete group).

Higher sustained loading accelerates fatigue degradation, leading to increased deflection and crack propagation. Coupled marine exposure further reduces stiffness and fatigue life by enabling seawater ingress and damage of the SFCB (resin degradation and steel core corrosion).

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Origami-Enhanced Dielectric Fluid Generator for Wave Energy Conversion

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1 Introduction

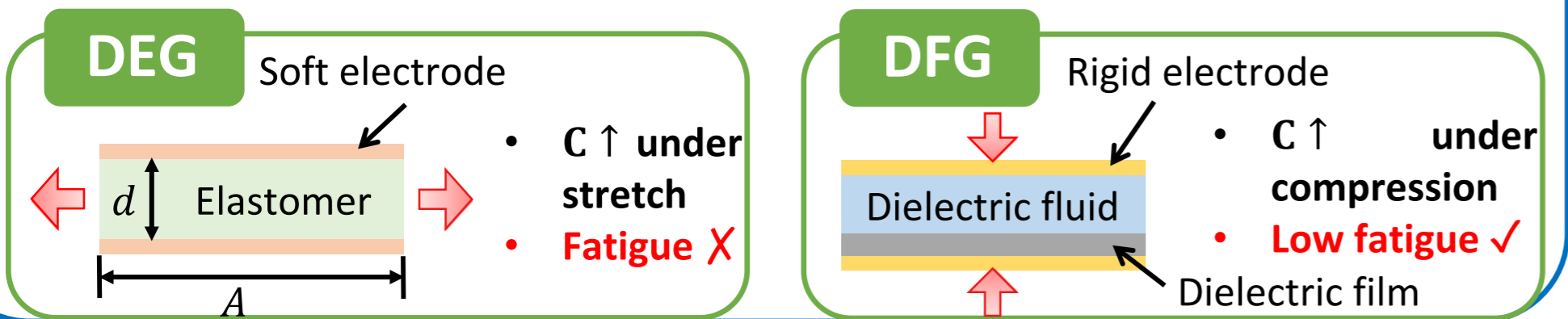


Ocean waves offer a vast, largely untapped, and sustainable energy resource. In the UK, wave energy has the potential to generate up to 30 TWh/year, about 10% of nation's electricity demand.

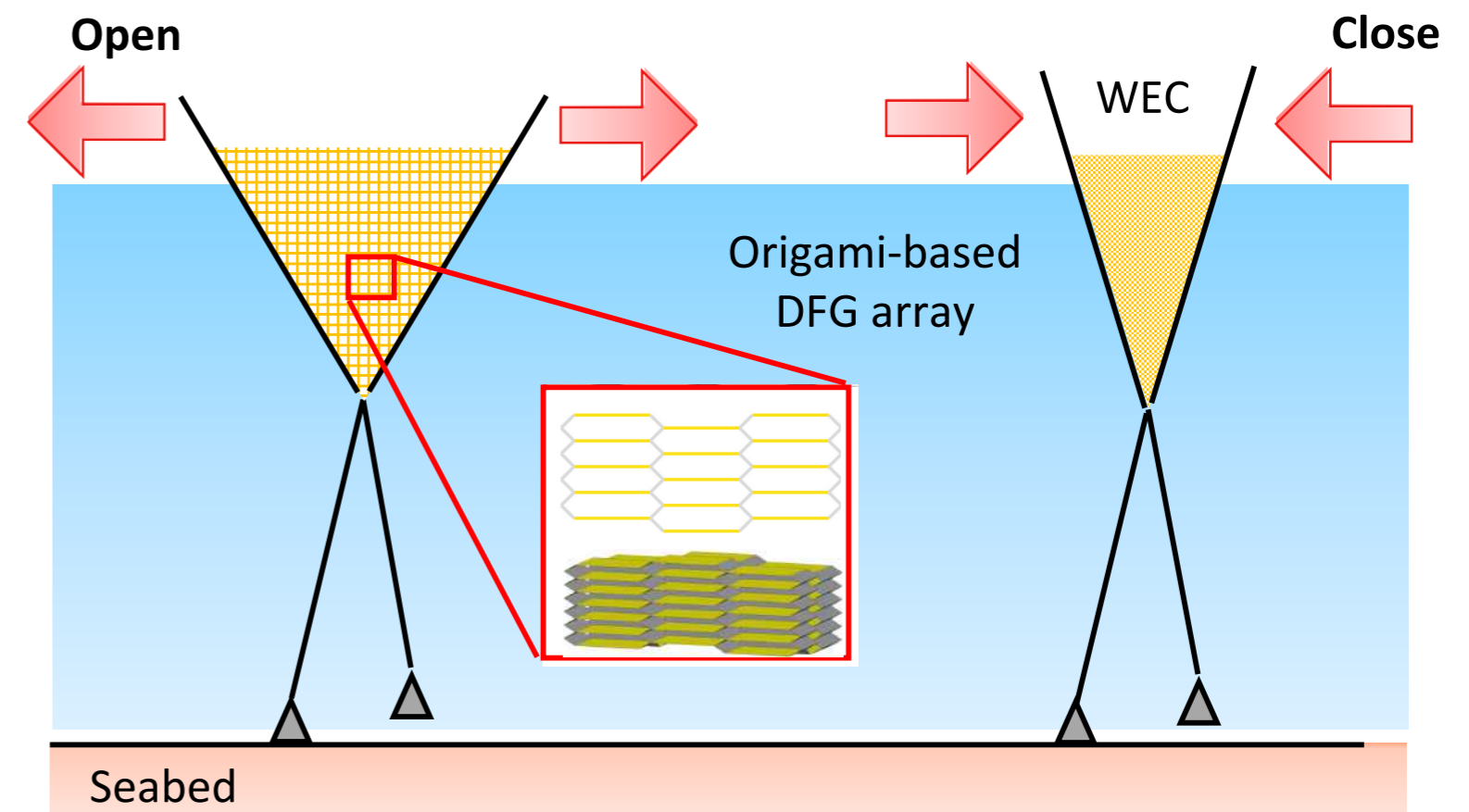
Dielectric elastomer generators (DEG) and dielectric fluid generators (DFG) use **mechanically variable capacitors** to convert wave motions into electricity. A parallel-plate capacitance is

$$C = \frac{\epsilon_0 \epsilon_r A}{d}$$

where ϵ_0 is vacuum permittivity and ϵ_r is relative permittivity.



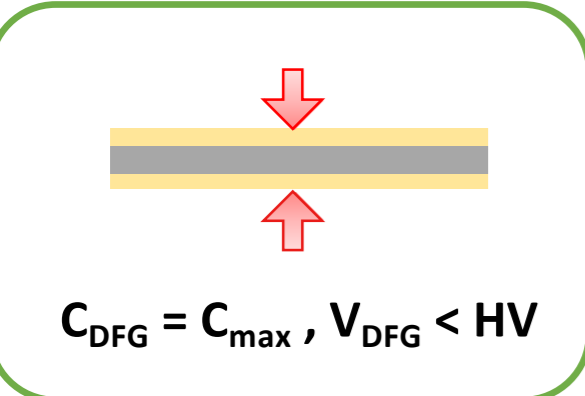
2 Why Origami?



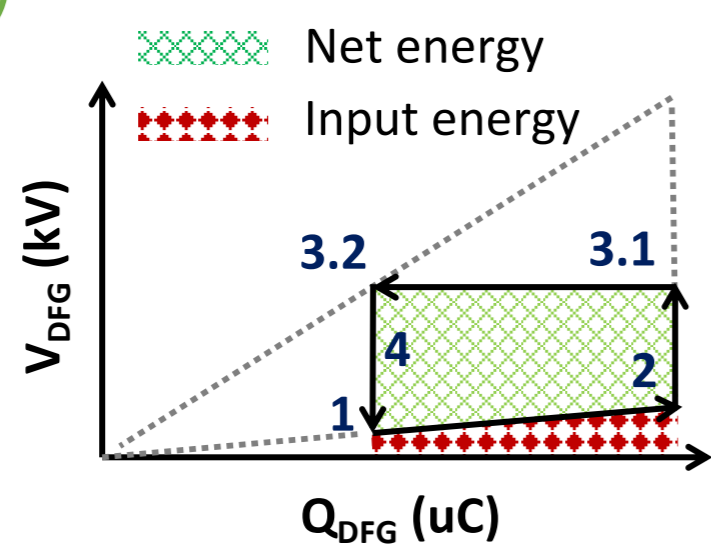
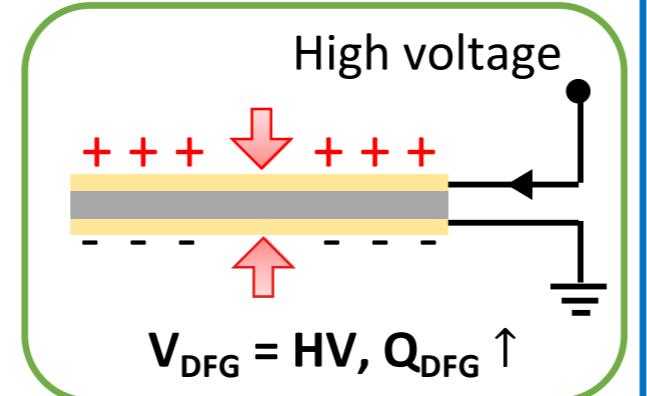
- ✓ Easily stackable for scalable arrays in wave energy converters.
- ✓ Stress isolated to flexible joints further enhances fatigue life.
- ✓ Precise control of electrode displacement improves efficiency.

3 DFG Working Cycle

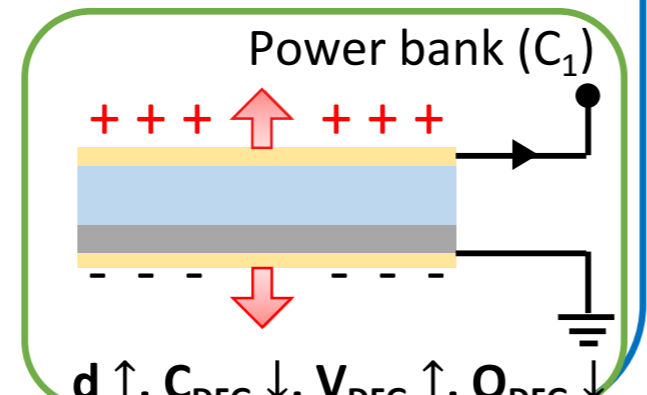
Step 1. Preparation



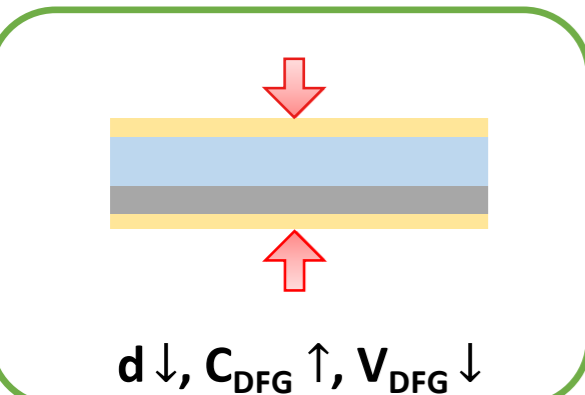
Step 2. Charging



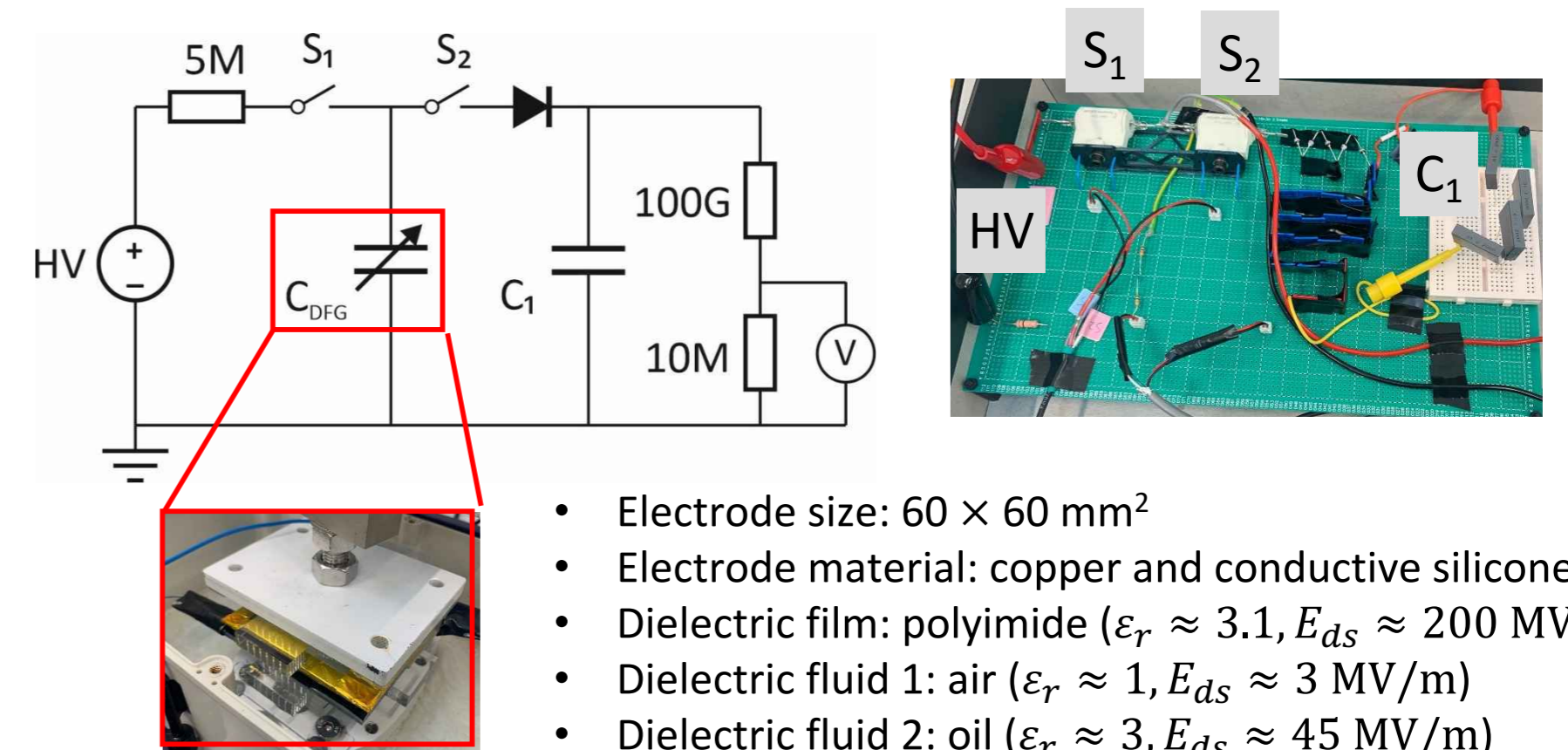
Step 3. Harvesting



Step 4. Return

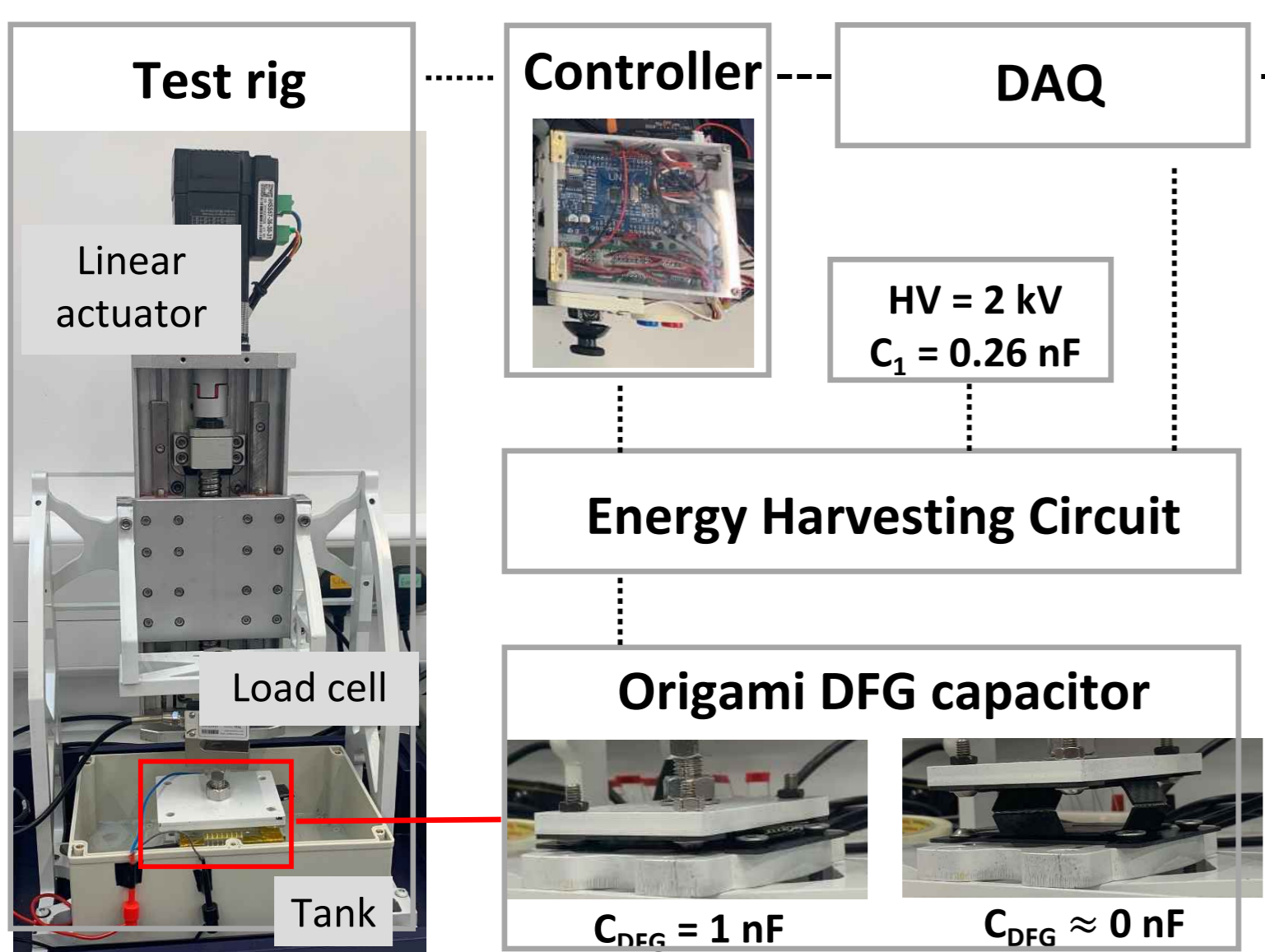


4 Circuit Design and Control



- Step 1** ⇒ S1 and S2 open, high voltage (HV) on, DFG idle
- Step 2** ⇒ S1 and S2 close, DFG is charged to HV
- Step 3** ⇒ S1 opens and S2 closes, DFG upper electrode lifts up
- Step 4** ⇒ S1 and S2 open, DFG upper electrode lowers down

5 Single DFG in One Wave Cycle



Actuation frequency (f) and speed (v) are tuneable to match wave dynamics. Electrode displacement (d) is precisely controlled.

